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Note: the stop time is computed as follows:  
 $12 = 2 * (\text{span}/2)$  [the delay of the pulse shaping filter plus the delay of the matched filter]; 4 = the number of data symbols; 8 = the number of samples/symbol. We subtract because the start time is  $t = 0.0$ .

## **Digital Communications: A Discrete-Time**

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xiii, first paragraph,  
“bare witness” should  
be “bear witness” Page  
xxi, last paragraph,  
“You know who you.”  
should be “You know

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who you are.” Chapter  
1 Page 3, second new  
paragraph, “Pittsburg”  
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to introduce and  
analyze digital  
communications -  
connecting continuous-  
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ideas.

## **Digital Communications: A Discrete-Time Approach by ...**

You start with a time  
function  $u$  of  $t$ , you  
substitute  $j\omega$  for  $s$ ,  
which gives you a  
function of frequency.

The inverse Fourier

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transform of that is what you get by taking the Fourier transform of  $u$  of  $t$ , and then substituting  $t$  for  $f$  in it. It's much harder to say it than to do. This time shift, you've all seen that. If you shift a function in time, the only thing that happens is you get this rotating term in it.

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The various blocks of a digital communication system are a hybrid of discrete-time signal

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generation and filtering, continuous-time signal processing at baseband frequencies, and continuous-time radio frequency (RF) up and down conversion.

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